

MATH CAMP: Lecture 1

1 Linear Algebra

Simultaneous Linear Equations:

Example:

$$\begin{aligned}3x_1 + 2x_2 &= 6 \\6x_1 + 7x_2 &= -2\end{aligned}$$

Now solve. Subtract twice first equation from second

$$\begin{array}{r}6x_1 + 7x_2 = -2 \\-6x_1 - 4x_2 = -12 \\ \hline 3x_2 = -14 \\ x_2 = \frac{-14}{3}\end{array}$$

Substitute this into equation 1

$$\begin{aligned}3x_1 + 2\left(\frac{-14}{3}\right) &= 6 \\3x_1 &= 6 + \frac{28}{3} = \frac{18 + 28}{3} = \frac{46}{3} \\x_1 &= \frac{46}{9}\end{aligned}$$

The next two equations are equivalent to the first two.

$$\begin{aligned}3x_1 + 2x_2 &= 6 \\3x_2 &= -14\end{aligned}$$

These are equivalent to the following pairs of equations.

$$\begin{aligned}x_1 + \frac{2}{3}x_2 = 2 \quad \text{or} \quad x_1 &= 2 - \frac{2}{3}\left(\frac{-14}{3}\right) = \frac{46}{9} \\x_2 &= \frac{-14}{3} \quad \quad \quad x_2 = \frac{-14}{3}\end{aligned}$$

The last pair is said to be *row reduced and in echelon form*. We want to do this more generally

$$\begin{aligned}a_{11}x_1 + a_{12}x_2 + \cdots + a_{1N}x_N &= y_1 \\a_{21}x_1 + a_{22}x_2 + \cdots + a_{2N}x_N &= y_2 \\&\vdots \\a_{M1}x_1 + a_{M2}x_2 + \cdots + a_{MN}x_N &= y_M\end{aligned}$$

The a_{mn} and y_n are numbers and x_1, \dots, x_N are unknown. In order to be more systematic we write the equation as:

$$Ax = y, \text{ where}$$

$$A = \begin{pmatrix} a_{11} & \cdots & a_{1N} \\ \vdots & & \vdots \\ a_{M1} & \cdots & a_{MN} \end{pmatrix} \text{ } M \times N \text{ matrix}$$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_N \end{pmatrix} \text{ } N\text{-vector of unknowns}$$

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_M \end{pmatrix} \text{ } M\text{-vector of numbers.}$$

Ax is the M -vector

$$\begin{matrix} a_{11}x_1 & + \cdots + & a_{1N}x_N \\ a_{21}x_1 & + \cdots + & a_{2N}x_N \\ \vdots & & \vdots \\ a_{M1}x_1 & + \cdots + & a_{MN}x_N \end{matrix}$$

Consider the following so called elementary operations on $M \times N$ matrix A :

1. Multiply a row of A by a non-zero number.
2. Replace a row by that row plus c times another row, where c is a non-zero number.
3. Interchange two rows.

If the $M \times N$ matrix B is obtained from A by any one of these operations, then A and B are equivalent in the sense the equations $Bx = 0$ and $Ax = 0$ have the same solutions. (Think this through.)

Similarly, if the $M \times (N + 1)$ matrix $(B \dot{=} z)$ is obtained from the $M \times (N + 1)$ matrix $(A \dot{=} y)$ by an elementary row operation, then the systems $Bx = z$ and $Ax = y$ have the same solutions.

Elementary row operations can transform any system $Ax = y$ into a system $Bx = z$ where

- a) the first non-zero entry in any row of B is 1, and
- b) each column of B that contains the leading non-zero entry of some row has all its other entries 0.

Definition: Such a matrix B is said to be *row-reduced*.

Example:

$$\begin{pmatrix} 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ is row reduced.}$$

Example:

$$\begin{aligned} & \begin{pmatrix} 3 & 2 & 1 \\ 6 & 4 & 2 \\ 6 & 8 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ 6 \\ 0 \end{pmatrix} \\ \rightarrow & \begin{pmatrix} 3 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 4 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ -6 \end{pmatrix} \\ \rightarrow & \begin{pmatrix} 1 & 2/3 & 1/3 \\ 0 & 0 & 0 \\ 0 & 1 & 3/4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -3/2 \end{pmatrix} \\ \rightarrow & \begin{pmatrix} 1 & 2/3 & 1/3 \\ 0 & 1 & 3/4 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -3/2 \\ 0 \end{pmatrix} \\ \rightarrow & \begin{pmatrix} 1 & 0 & -1/6 \\ 0 & 1 & 3/4 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 \\ -3/2 \\ 0 \end{pmatrix} \end{aligned}$$

The matrix $\begin{pmatrix} 1 & 0 & -1/6 \\ 0 & 1 & 3/4 \\ 0 & 0 & 0 \end{pmatrix}$ is an example of a row reduced echelon matrix.

Definition: A matrix is a *row reduced echelon matrix* if:

- a) it is row reduced,
- b) any row of zeros lies below all non-zero rows, and
- c) if the first r rows are non-zero and the leading non-zero entry of row m is in column n_m for $m = 1, \dots, r$ then $n_1 < n_2 < \dots < n_r$.

Example: The matrix $\begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ is a row reduced echelon matrix

Theorem: Every matrix is equivalent to a row reduced echelon matrix.

Proof: This may be achieved by elementary row operations. ■

Theorem: If A is an $M \times N$ matrix and $M < N$, then the system $Ax = 0$ has a non-zero solution.

Proof: Let B be a row reduced echelon matrix equivalent to A . $Ax = 0 \iff Bx = 0$. Let r be the number of non-zero rows of B . Then $r \leq M < N$ and rows $1, \dots, r$ are

the non-zero rows of B . For $1 \leq m \leq r$, let the leading non-zero entry of row m be in column n_m , where $n_1 < n_2 < \dots < n_r$. Since $r < N$, there is an n such that $1 \leq n \leq N$ and $n \neq n_m$ for any m . For such an n , let $x_n = 1$. For k such that $1 \leq k \leq N$, let $x_k = 0$, if $k \neq n_m$, for all m . It is now possible to solve for x_n , for $n = n_1, \dots, n_r$, so that $Bx = 0$. Then $Ax = 0$ and $x \neq 0$. ■

Theorem: If A is an $N \times N$ matrix and if $Ax = 0$ has no non-zero solution, then A is row equivalent to the $N \times N$ identity matrix $\begin{pmatrix} 1 & \cdot & \cdot & 0 \\ 0 & \cdot & \cdot & 1 \end{pmatrix} = I$.

Proof: Let B be a row reduced echelon matrix that is row equivalent to A . $Bx = 0$ has no non-zero solution. Hence the number of non-zero rows of B is N . Hence, $B = I$. ■

2 Vector Spaces

Consider $R^N = \{v = (v_1, \dots, v_N) \mid v_n \in R, \text{ for all } n\}$, where R is the set of real numbers. We can define the following operations on R^N . If v and w belong to R^N , $v + w = (v_1, \dots, v_N) + (w_1, \dots, w_N) = (v_1 + w_1, \dots, v_N + w_N)$. If $c \in R$ and $v \in R^N$, $cv = c(v_1, \dots, v_N) = (cv_1, \dots, cv_N)$. Let $0 = (0, 0, \dots, 0) \in R^N$. Observe that

- a) $x + y \in R^N$, if $x \in R^N$ and $y \in R^N$
- b) $x + y = y + x$,
- c) there is a $0 \in R^N$ and $0 + x = x$, for all $x \in R^N$,
- d) for all $x \in R^N$, there is a unique $-x \in R^N$ such that $x + (-x) = 0$,
- e) $1x = x$, for $x \in R^N$
- f) $(c_1 c_2)x = c_1(c_2 x)$, for all numbers c_1 and c_2 and for all $x \in R^N$,
- g) $c(x + y) \equiv cx + cy$, for numbers c and for x and y in R^N ,
- h) $(c_1 + c_2)x = c_1 x + c_2 x$, for all numbers c_1 and c_2 and for all $x \in R^N$.

Definition: A *vector space* consists of a set, V , together with operations of addition and multiplication by numbers, denoted $x + y$ and rx , where $x \in V, y \in V$ and $r \in R$ and these operations satisfy (a)–(h) above with R^N everywhere replaced by V .

Definition: W is a *subspace* of V , if $W \subset V$ and W is a vector space under the operations on V .

Note: $W \subset V$ is a subspace of V if $v + w \in W$, for all $v, w \in W$, and if $cv \in W$ whenever $c \in R$ and $v \in W$.

Example: $V = \{f : [0, 2\pi] \rightarrow R \mid f(0) = f(2\pi)\}$ is a vector space under the operations $(f + g)(s) = f(s) + g(s)$, for all $s \in [0, 2\pi]$ and $(cf)(s) = cf(s)$, for all s .

$W = \{a \sin + b \cos \mid a \in R \text{ and } b \in R\}$ is a subspace of V . W is the linear span of \sin and \cos .

Definition: If V is vector space, $v \in V$ is said to be a *linear combination* of $w_1, \dots, w_N \in V$, if there are numbers c_1, \dots, c_N such that $v = c_1 w_1 + \dots + c_N w_N$.

Definitions: If $w_1, \dots, w_N \in V$, their *linear span* is the set of all linear combinations of w_1, \dots, w_N . The linear span of w_1, \dots, w_N is a subspace of V and is the smallest subspace containing w_1, \dots, w_N . The vectors, w_1, \dots, w_N are said to span V , if V is the linear span of w_1, \dots, w_N .

Now I try to get at the idea of the *dimension* of a vector space.

Definition: Vectors v_1, \dots, v_N in V are *linearly dependent* if there exist numbers c_1, \dots, c_N , not all zero, such that $c_1 v_1 + \dots + c_N v_N = 0$.

Definition: Vectors v_1, \dots, v_N in V are *linearly independent* if there are not dependent.

Example: $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ are dependent in R^3 , since

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ are independent, since

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} \Rightarrow c_1 = c_2 = c_3 = 0$$

Example: \sin and \cos are independent, for suppose that $a \sin + b \cos = 0$. Then $0 = a \sin(\pi/2) + b \cos(\pi/2) = a$ and $0 = a \sin(0) + b \cos(0) = b$, so that $a = b = 0$, $\sin + 2 \cos$ and $-2 \sin - 4 \cos$ are dependent, since $2(\sin + 2 \cos) + (-2 \sin - 4 \cos) = 0$

Definition: A *basis* for a vector space V is a set of linearly independent vectors in V that spans V .

Example: Let

$$e_n = (0, \dots, 0, 1, 0, \dots, 0) \in R^N$$

\uparrow
 n th slot

e_1, \dots, e_N is the *standard basis* for R^N .

Theorem: If v_1, \dots, v_M span a vector space V , then any independent set of vectors in V has no more than M elements.

Proof: I must show that if $N > M$ and w_1, \dots, w_N are in V , then w_1, \dots, w_N are linearly dependent. Since v_1, \dots, v_M span V , $w_n = \sum_{m=1}^M a_{mn}v_m$, for all n and for some numbers a_{1n}, \dots, a_{Mn} . If x_1, \dots, x_N are numbers, then

$$\begin{aligned} x_1w_1 + \cdots + x_Nw_N &= \sum_{n=1}^N x_nw_n = \sum_{n=1}^N x_n \sum_{m=1}^M a_{mn}v_m \\ &= \sum_{n=1}^N \sum_{m=1}^M a_{mn}x_nv_m = \sum_{m=1}^M \left(\sum_{n=1}^N a_{mn}x_n \right) v_m \end{aligned}$$

Since $N > M$, a previous theorem implies that there exist numbers x_1, \dots, x_N not all zero such that $\sum_{n=1}^N a_{mn}x_n = 0$ for $m = 1, \dots, M$. Hence, $x_1w_1 + \cdots + x_Nw_N = 0$ and w_1, \dots, w_N are linearly dependent. ■

Definition: A vector space is *finite dimensional*, if it has a finite basis.

Corollary: If V is a finite dimensional vector space, then any two bases have the same number of elements.

Proof: If v_1, \dots, v_M and w_1, \dots, w_N are bases, then $N \leq M$ and $M \leq N$. ■

Definition: The dimension of V is $\dim V =$ the number of vectors in a bases for V .

Lemma: Let v_1, \dots, v_M in V be linearly independent and let w in V not belong to the span of v_1, \dots, v_M . Then v_1, \dots, v_M, w are linearly independent.

Proof: Suppose that $c_1v_1 + \cdots + c_Mv_M + bw = 0$. If $b \neq 0$, then $w = \frac{-c}{b}v_1 - \cdots - \frac{c_M}{b}v_M \in \text{span}(v_1, \dots, v_M)$. This contradiction implies that $b = 0$. Therefore, $c_1v_1 + \cdots + c_Mv_M = 0$. Since, v_1, \dots, v_M are linearly independent, $c_m = 0$, for all m . ■

Theorem: If W is a subspace of a vector space V of finite and positive dimension and $W \neq V$, then $\dim W < \dim V$.

Proof: Let $M = \dim W$ and $N = \dim V$. I must show that $M < N$. If $W = \{0\}$ then $\dim W = 0 < \dim V$. Suppose that $W \neq \{0\}$. If w_1, \dots, w_M are linearly independent vectors in W , they are linearly independent in V and so $M \leq N$. Therefore, there is a linearly independent set of vectors in W with a largest number of elements, say w_1, \dots, w_r . By the previous lemma w_1, \dots, w_r is a basis for W and $r = \dim W$. Since $W \neq V$, there is a v in V such that $v \notin W$. By the previous lemma, w_1, \dots, w_r, v are independent and hence $N \geq M + 1 > M$. ■

Theorem: If v_1, \dots, v_N is a basis for V and $v \in V$, then the numbers c_1, \dots, c_N , such that $v = \sum_{n=1}^N c_n v_n$ are unique.

Proof: $\sum_{n=1}^N c_n v_n = v = \sum_{n=1}^N a_n v_n \implies \sum_{n=1}^N (c_n - a_n) v_n = 0 \implies c_n - a_n = 0$, for all n , since v_1, \dots, v_N are independent. ■